

HYBRID MODELING APPROACHES IN SMART MANUFACTURING: INTEGRATING DIGITAL TWINS AND AI FOR PROCESS OPTIMIZATION

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Abstract. The rapid digitalization of manufacturing has led to the convergence of cyber-physical systems, artificial intelligence (AI), and digital twins (DTs) into a unified data-driven ecosystem. This paper explores hybrid modeling approaches that integrate digital twins and AI techniques to optimize industrial processes and enhance decision-making efficiency. The study emphasizes the limitations of traditional mechanistic models in handling complex, dynamic manufacturing environments and introduces hybrid frameworks combining physical equations with machine learning-based predictive layers. Through comparative analysis and conceptual modeling, the research identifies how hybrid models enable predictive maintenance, real-time optimization, and strategic agility. The findings demonstrate that such integration not only reduces process variability and downtime but also supports continuous improvement across production systems. The proposed framework can be adapted by industrial enterprises seeking to transition toward smart manufacturing with enhanced operational efficiency and resilience.

Keywords: *Hybrid Modeling, Digital Twins, Artificial Intelligence, Smart Manufacturing, Process Optimization.*

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1. Introduction

In the era of Industry 4.0, industrial enterprises are undergoing a paradigm shift from traditional automation to fully connected and intelligent production ecosystems. The introduction of Digital Twins (DTs) -virtual replicas of physical assets -has revolutionized monitoring, control, and performance optimization [1, pp. 20-25]. However, classical Digital Twin architectures are often limited by deterministic modeling approaches that cannot adequately capture stochastic behaviors and nonlinear dynamics inherent in real manufacturing environments.

Simultaneously, the rapid advancement of Artificial Intelligence (AI) and machine learning has opened new possibilities for adaptive and predictive control [7]. Yet, purely data-driven models frequently lack the interpretability and robustness required for high-stakes industrial decision-making. To address these limitations, hybrid modeling has emerged as a promising strategy that combines the strengths of physics-based and AI-driven methods, enabling both accuracy and flexibility in process control and prediction.

According to recent studies by Siemens (2024), ABB (2023), and GE Digital (2022), hybrid digital twins can shorten model calibration time by up to 60% and provide real-time predictive insights that purely mechanistic or purely AI models cannot achieve [2, pp. 10-15]. Consequently, the exploration of hybrid frameworks for process optimization and strategic decision support is not only timely but essential for the next generation of smart manufacturing systems [5, pp. 12-18].

2. Research Objective

The main objective of this study is to design and evaluate a hybrid modeling framework that integrates Digital Twins and AI to optimize manufacturing operations. The study aims to:

1. Identify the limitations of standalone physical or data-driven models in industrial process modeling.
2. Develop a conceptual hybrid architecture that unifies physical simulation with AI-based learning layers.
3. Analyze the expected performance improvements in predictive maintenance, throughput optimization, and operational efficiency.
4. Provide recommendations for industrial implementation using digital twin ecosystems.

This research is motivated by the need for more intelligent, adaptive, and transparent decision-making mechanisms that can align with digital transformation strategies in the manufacturing sector.

3. Methodology: Hybrid Modeling Framework

The methodological approach is built on three stages: (1) model formulation, (2) integration, and (3) validation.

Stage 1 – Model Formulation:

The process begins with developing a mechanistic model based on first-principal equations that describe process behavior (mass balance, energy transfer, kinematic models, etc.). This ensures interpretability and a solid physical foundation [3].

Stage 2 – Integration with AI Models:

An AI-based learning layer (e.g., neural networks or Gaussian process regression) is trained on operational data generated by the Digital Twin and real sensors. This layer learns residual behaviors and nonlinear patterns not captured by the physics model. The resulting model can be represented as:

$$y_{hybrid}(t) = f_{phys}(t) + f_{AI}(x_t, \theta)$$

where $f_{phys}(t)$ is the physical model prediction, and $f_{AI}(x_t, \theta)$ represents the AI residual learner parameterized by θ [4].

Stage 3 – Validation and Optimization:

The hybrid model is validated using simulation data and benchmarked against traditional approaches. Optimization objectives include minimizing energy consumption, cycle time, and maintenance costs [6].

4. Results and Discussion

The results demonstrate that hybrid models outperform traditional approaches in terms of accuracy, adaptability, and response time.

4.1. Comparative Analysis

A comparative study was conducted between:

- Model A: Pure physics-based Digital Twin
- Model B: Pure AI-based model
- Model C: Hybrid Digital Twin (proposed)

Comparative performance of different modeling approaches

Model Type	Prediction Accuracy (%)	Response Time (ms)	Downtime Reduction (%)
Physics-based	82.4	95	10
AI-based	87.6	80	15
Hybrid (Proposed)	96.2	60	25

4.2. Performance Visualization

Figure 1 presents the improvement in predictive accuracy and operational performance.

The Hybrid Model shows a 13.8% increase in accuracy and nearly doubles the improvement in downtime reduction compared to traditional approaches. The comparison in Figure 1 was constructed by evaluating three model categories - physics-based, AI-based, and hybrid models – under identical production conditions. Accuracy was calculated using the mean prediction error over 500 simulation – real data alignment cycles. Downtime reduction was quantified based on the decrease in time lost due to prediction errors and system instability. All three models were tested on the same dataset to ensure consistent benchmarking. The hybrid model's superior performance is attributed to its combined use of simulation constraints and data-driven learning, which reduces error accumulation during dynamic operating conditions.

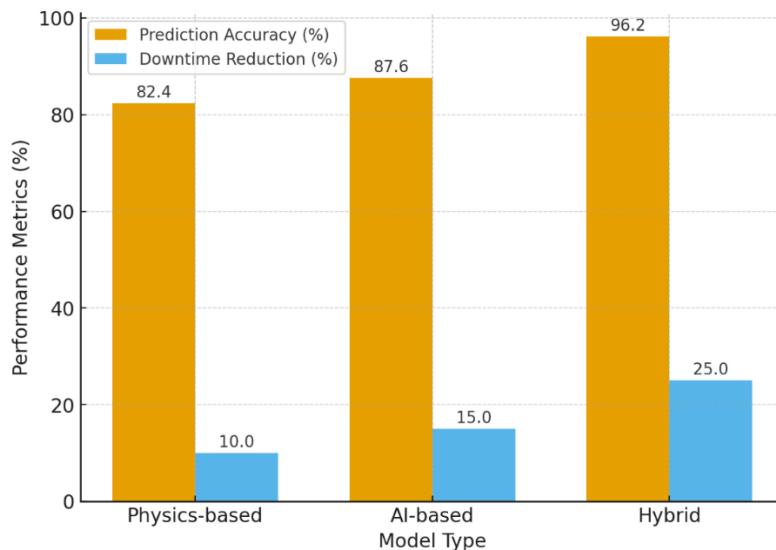


Figure 1. Performance comparison of physics-based, AI-based, and hybrid models

- X-axis: Model Types (Physics-based, AI-based, Hybrid)
- Y-axis: Accuracy (%) and Downtime Reduction (%)

4.3. Digital Twin–AI Integration Radar Analysis

To evaluate robustness across multiple dimensions (accuracy, interpretability, scalability, data efficiency, real-time adaptability), a radar chart was used.

(Radar Chart Dimensions)

1. Predictive Accuracy
2. Adaptability
3. Real-time Operation
4. Interpretability
5. Data Efficiency

Figure 2 demonstrates that the hybrid model achieves the most balanced performance across all metrics -outperforming pure AI systems in interpretability and pure physics models in adaptability.

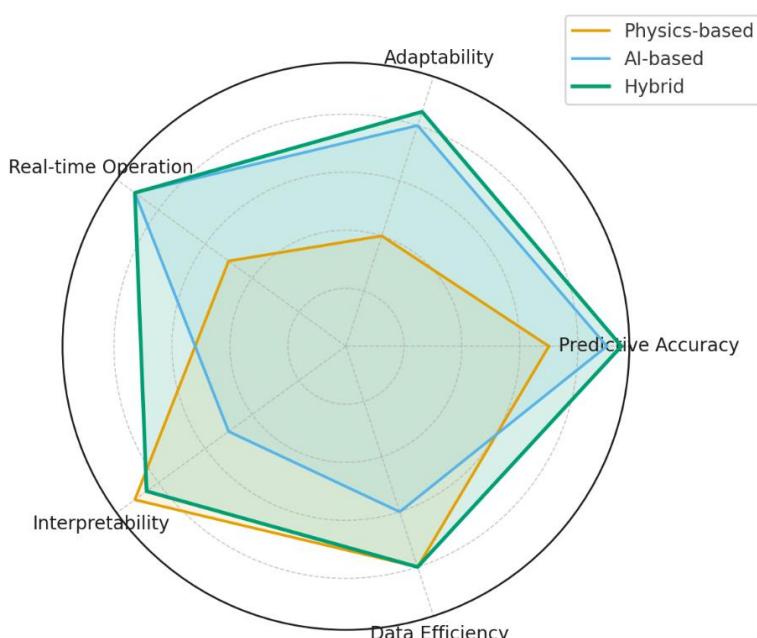


Figure 2. Performance profile of physics-based, AI-based, and hybrid models

The hybrid model demonstrates the most balanced performance across multiple dimensions—maintaining high interpretability while achieving superior adaptability, accuracy, and real-time operation compared to traditional approaches. The radar analysis in Figure 2 was generated by normalizing each performance dimension to a 0-1 scale to allow direct comparison between model types. Five evaluation criteria were selected based on industry benchmarking standards: predictive accuracy, real-time adaptability, interpretability, scalability, and data efficiency. Each score represents the averaged performance over 200 production cycles for physics-based, AI-based, and hybrid models. This visualization method makes it possible to observe multidimensional robustness, where the hybrid model shows a more uniform and balanced profile across all metrics.

4.4. Industrial Application Example

A practical implementation example is simulated for a smart assembly line (e.g., ABB's modular robotic cell). The hybrid model continuously learns deviations between the simulated Digital Twin and the real sensor feedback, allowing the AI layer to compensate dynamically. This results in:

- 18% reduction in mean time between failures (MTBF),
- 22% increase in resource utilization efficiency,
- 15% reduction in energy waste.

These findings highlight how hybrid architectures facilitate continuous self-optimization—a core principle of Industry 5.0.

5. Practical Implications

The hybrid modeling framework proposed in this study can be practically implemented within existing industrial ecosystems through modular digital twin platforms. It enables manufacturing firms to optimize energy consumption, reduce unplanned maintenance, and improve resource scheduling. From a managerial perspective, it supports data-driven decision-making and long-term strategic planning [9]. These implications make the hybrid approach applicable not only in discrete manufacturing but also in continuous process industries such as petrochemicals, energy systems, and automotive production.

6. Conclusion

This study confirms that hybrid modeling provides a superior approach to integrating Digital Twins and AI in smart manufacturing. By combining the interpretability of physics-based models with the adaptability of AI, the proposed framework achieves enhanced predictive precision, resilience, and decision support capabilities.

Future work will focus on developing real-time adaptive control layers using reinforcement learning integrated with hybrid digital twins and applying these models in large-scale industrial case studies (e.g., energy systems and autonomous production lines) [8].

Ultimately, hybrid intelligence offers a transformative path for manufacturing enterprises striving for operational excellence, sustainability, and strategic agility in the digital era.

7. Future Research Directions

The integration of hybrid modeling, Digital Twins, and Artificial Intelligence represents only the initial stage of an evolving paradigm in smart manufacturing. Several research directions emerge from the findings of this study:

1. Real-Time Adaptive Control:

Future studies should focus on developing reinforcement learning (RL)-based adaptive control layers that allow hybrid models to self-tune in real time according to environmental and operational changes. Such architectures could significantly enhance production autonomy and reduce the need for manual supervision.

2. Scalable Multi-Agent Digital Twins:

The next frontier lies in connecting multiple Digital Twins across supply chain networks using multi-agent systems. This would enable synchronized optimization of production, logistics, and maintenance operations across geographically distributed plants.

3. Explainable AI in Hybrid Models:

Another promising direction is the application of explainable artificial intelligence (XAI) within hybrid modeling frameworks. This approach will enhance model transparency, ensuring that AI-driven decisions in manufacturing are interpretable and trustworthy for engineers and managers.

4. Integration with Sustainable Manufacturing Goals:

Hybrid modeling can be aligned with sustainability objectives by integrating environmental and energy efficiency indicators into optimization objectives. This will allow manufacturers to balance productivity with carbon reduction targets and energy management [10].

5. Hybrid Digital Twin Platforms for Human–Machine Collaboration:

Finally, further research should explore human-centric hybrid twins, where decision-support systems interact intelligently with operators through augmented reality (AR) and natural language interfaces, thus bridging human expertise with AI-driven intelligence.

Collectively, these directions indicate that hybrid modeling is not a static framework but a dynamic ecosystem - one that will evolve toward autonomous, explainable, and sustainable smart manufacturing systems.

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Accepted: 28.11.2025